Nearest Neighbor Predictors

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Approximate conditional means and probabilities

- Optimal theoretical predictors often involve conditional (on the input vector) mean response or probabilities for the *K* possible values
- Approximations to these based on training data provide methods useable in practice
- "Nearest neighbor" approximations provide a full spectrum of ultimate predictor complexities/flexibilities (of the type needed in matching complexity to training set information content)

Motivation

• One might naively hope to use approximations like

$$E[y | \mathbf{x}] \approx \frac{1}{\# \text{ of } \mathbf{x}_i = \mathbf{x}} \sum_{i \text{ s.t. } \mathbf{x}_i = \mathbf{x}} y_i \text{ or } P[y = a | \mathbf{x}] \approx \frac{1}{\# \text{ of } \mathbf{x}_i = \mathbf{x}} \sum_{i \text{ s.t. } \mathbf{x}_i = \mathbf{x}} I[y_i = a]$$

but they will rarely work in practice, since typically counts of matching inputs in the training set are very small (if not 1)

• Roughly speaking, one might want to replace $\mathbf{x}_i = \mathbf{x}$ above with $\mathbf{x}_i \approx \mathbf{x}$

• One means of doing this is built on k-nearest neighborhoods $n_k(x) = ext{the set of } k ext{ inputs } x_i ext{ in the training set closest to } x ext{ in } \Re^p$

k-nn approximations

• Based on this reasoning, one is led to k-nn approximations

$$\mathbf{E}[y \mid \mathbf{x}] \approx \frac{1}{k} \sum_{i \text{ s.t. } \mathbf{x}_i \in n_k(\mathbf{x})} y_i \text{ or } P[y = a \mid \mathbf{x}] \approx \frac{1}{k} \sum_{i \text{ s.t. } \mathbf{x}_i \in n_k(\mathbf{x})} I[y_i = a]$$

• These lead to the approximately optimal SEL predictor $\hat{f}(\mathbf{x}) \approx \frac{1}{k} \sum_{i \text{ s.t. } \mathbf{x}_i \in n_k(\mathbf{x})} y_i$

and approximately optimal 0-1 loss classifier

$$\hat{f}(\mathbf{x}) \approx \underset{a}{\operatorname{argmax}} \# i \text{ s.t. } \mathbf{x}_i \in n_k(\mathbf{x}) \text{ and } y_i = a$$

k-nn SEL prediction





k-nn predictor complexity

- k-nn predictor complexity/flexibility decreases with increasing k (after all, k=1 simply predicts according to the single closest training case—a highly erratic proposition as one looks across the input space—while k=N produces constant predictors)
- The neighborhood size should thus be chosen to match complexity with real training set information content